

Process Dynamics Modeling And Control

An Introduction to System Modeling and Control Techniques of Model-based Control Hybrid Electric Vehicle System Modeling and Control Modeling and Control of Discrete-event Dynamic Systems Discrete Event Systems: Modeling and Control Process Dynamics, Modeling, and Control Modeling and Control of Sustainable Power Systems Fuzzy Decision Making in Modeling and Control Fuzzy Modeling and Control: Theory and Applications Modeling and Control of Engines and Drivelines Modeling and Control of Batch Processes Modeling and Control of Precision Actuators Modeling and Control in the Biomedical Sciences Modeling and Simulation for Automatic Control Introduction to Control Engineering Fractional-order Modeling and Control of Dynamic Systems Dynamic Modeling and Predictive Control in Solid Oxide Fuel Cells Efficient Modeling and Control of Large-Scale Systems Introduction to Modeling and Control of Internal Combustion Engine Systems Dynamics Of Mechatronics Systems: Modeling, Simulation, Control, Optimization And Experimental Investigations John Chiasson Coleman Brosilow Wei Liu Branislav Hriň S. Balemi Babatunde Ayodeji Ogunnaike Lingfeng Wang Joao M. C. Sousa Fernando Matŕa Lars Eriksson Prashant Mhaskar Tan Kok Kiong H. T. Banks Olav Egeland Ajit K. Mandal Aleksei Tepljakov Biao Huang Javad Mohammadpour Lino Guzzella Jan Awrejcewicz

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a practical and straightforward exploration of the basic tools for the modeling analysis and design of control systems in an introduction to system modeling and control dr chiasson delivers an accessible and intuitive guide to understanding modeling and control for students in electrical mechanical and aerospace aeronautical engineering the book begins with an introduction to the need for control by describing how an aircraft flies complete with figures illustrating roll pitch and yaw control using its ailerons elevators and rudder respectively the book moves on to rigid body dynamics about a single axis gears cart rolling down an incline and then to modeling dc motors dc tachometers and optical encoders using the transfer function representation of these dynamic models pid controllers are introduced as an effective way to track step inputs and reject constant disturbances it is further shown how any transfer function model can be stabilized using output pole placement and on how two degree of freedom controllers can be used to eliminate overshoot in step responses bode and nyquist theory are then presented with an emphasis on how they give a quantitative insight into a control system s robustness and sensitivity an introduction to system modeling and control closes with chapters on modeling an inverted pendulum and a magnetic levitation system trajectory tracking control using state feedback and state estimation in addition the book offers a complete set of matlab simulink files for examples and problems included in the book a set of lecture slides for each chapter a solutions manual with recommended problems to assign an analysis of the robustness and sensitivity of four different controller designs for an inverted pendulum cart pole perfect for electrical mechanical and aerospace aeronautical engineering students an introduction to system modeling and control will also be an invaluable addition to the libraries of practicing engineers

annotation in this book two of the field s leading experts bring together powerful advances in model based control for chemical process engineering from start to finish coleman brosilow and babu joseph introduce practical approaches designed to solve real world problems not just theory the book contains extensive examples and exercises and an accompanying cd rom contains hands on matlab files that supplement the examples and help readers solve the exercises a feature found in no other book on the topic

this new edition includes approximately 30 new materials covering the following information that has been added to this important work extends the contents on li ion batteries detailing the positive and negative electrodes and characteristics and other components including binder electrolyte separator and foils and the structure of li ion battery cell nickel cadmium batteries are deleted adds a new section presenting the modelling of multi mode electrically variable transmission which gradually became the main structure of the hybrid power train during the last 5 years newly added chapter on noise and vibration of hybrid vehicles introduces the basics of vibration and noise issues associated with power train driveline and vehicle vibrations and addresses control solutions to reduce the noise and vibration levels chapter 10 chapter 9 of the first edition is extended by presenting epa and un newly required test drive schedules and test procedures for hybrid electric mileage calculation for window sticker

considerations in addition to the above major changes in this second edition adaptive charging sustaining point determination method is presented to have a plug in hybrid electric vehicle with optimum performance

discrete event dynamic systems deds permeate our world they are of great importance in modern manufacturing processes transportation and various forms of computer and communications networking this book begins with the mathematical basics required for the study of deds and moves on to present various tools used in their modeling and control industrial examples illustrate the concepts and methods discussed making this book an invaluable aid for students embarking on further courses in control manufacturing engineering or computer studies

research of discrete event systems is strongly motivated by applications in flex ible manufacturing in traffic control and in concurrent and real time software verification and design just to mention a few important areas discrete event system theory is a promising and dynamically developing area of both control theory and computer science discrete event systems are systems with non numerically valued states inputs and outputs the approaches to the modelling and control of these systems can be roughly divided into two groups the first group is concerned with the automatic design of controllers from formal specifications of logical requirements this re search owes much to the pioneering work of p j ramadge and w m wonham at the beginning of the eighties the second group deals with the analysis and op timization of system throughput waiting time and other performance measures for discrete event systems the present book contains selected papers presented at the joint workshop on discrete event systems wodes 92 held in prague czechoslovakia on au gust 26 28 1992 and organized by the institute of information theory and au tomation of the czechoslovak academy of sciences prague czechoslovakia by the automatic control laboratory of the swiss federal institute of technology eth zurich switzerland and by the department of computing science of the university of groningen groningen the netherlands

this text offers a modern view of process control in the context of today s technology it provides the standard material in a coherent presentation and uses a notation that is more consistent with the research literature in process control topics that are unique include a unified approach to model representations process model formation and process identification multivariable control statistical quality control and model based control this book is designed to be used as an introductory text for undergraduate courses in process dynamics and control in addition to chemical engineering courses the text would also be suitable for such courses taught in mechanical nuclear industrial and metallurgical engineering departments the material is organized so that modern concepts are presented to the student but details of the most advanced material are left to later chapters the text material has been developed refined and classroom tested over the last 10 15 years at the university of wisconsin and more recently at the university of delaware as part of the course at wisconsin a laboratory has been developed to allow the students hands on experience with measurement instruments real time computers and experimental process dynamics and control problems

the concept of the smart grid promises the world an efficient and intelligent approach of managing energy production transportation and consumption by incorporating intelligence efficiency and optimality into the power grid both energy providers and consumers can take advantage of the convenience reliability and energy savings achieved by real time and intelligent energy management to this end the current power grid is experiencing drastic changes and upgrades for instance more significant green energy resources such as wind power and solar power are being integrated into the power grid and higher energy storage capacity is being installed in order to mitigate the intermittency issues brought about by the variable energy resources at the same time novel power electronics technologies and operating strategies are being invented and adopted for instance flexible ac transmission systems and phasor measurement units are two promising technologies for improving the power system reliability and power quality demand side management will enable the customers to manage the power loads in an active fashion as a result modeling and control of modern power grids pose great challenges due to the adoption of new smart grid technologies in this book chapters regarding representative applications of smart grid technologies written by world renowned experts are included which explain in detail various innovative modeling and control methods

decision making and control are two fields with distinct methods for solving problems and yet they are closely related this book bridges the gap between decision making and control in the field of fuzzy decisions and fuzzy control and discusses various ways in which fuzzy decision making methods can be applied to systems modeling and control fuzzy decision making is a powerful paradigm for dealing with human expert knowledge when one is designing fuzzy model based controllers the combination of fuzzy decision making and fuzzy control in this book can lead to novel control schemes that improve the existing controllers in various ways the following applications of fuzzy decision making methods for designing control systems are considered oco fuzzy decision making for enhancing fuzzy modeling the values of important parameters in fuzzy modeling algorithms are selected by using fuzzy decision making oco fuzzy decision making for designing signal based fuzzy controllers the controller mappings and the defuzzification steps can be obtained by decision making methods oco fuzzy design and performance specifications in model based control fuzzy constraints and fuzzy goals are used oco design of model based controllers combined with fuzzy decision modules human operator experience is incorporated for the performance specification in model based control the advantages of bringing together fuzzy control and fuzzy decision making are shown with multiple examples from real and simulated control systems

much work on fuzzy control covering research development and applications has been developed in europe since the 90 s nevertheless the existing books in the field are compilations of articles without interconnection or logical structure or they express the personal point of view of the author this book compiles the developments of researchers with demonstrated experience in the field of fuzzy control following a logic structure and a

unified the style the first chapters of the book are dedicated to the introduction of the main fuzzy logic techniques where the following chapters focus on concrete applications this book is supported by the eusflat and cea ifac societies which include a large number of researchers in the field of fuzzy logic and control the central topic of the book fuzzy control is one of the main research and development lines covered by these associations

control systems have come to play an important role in the performance of modern vehicles with regards to meeting goals on low emissions and low fuel consumption to achieve these goals modeling simulation and analysis have become standard tools for the development of control systems in the automotive industry modeling and control of engines and drivelines provides an up to date treatment of the topic from a clear perspective of systems engineering and control systems which are at the core of vehicle design this book has three main goals the first is to provide a thorough understanding of component models as building blocks it has therefore been important to provide measurements from real processes to explain the underlying physics to describe the modeling considerations and to validate the resulting models experimentally second the authors show how the models are used in the current design of control and diagnosis systems these system designs are never used in isolation so the third goal is to provide a complete setting for system integration and evaluation including complete vehicle models together with actual requirements and driving cycle analysis key features covers signals systems and control in modern vehicles covers the basic dynamics of internal combustion engines and drivelines provides a set of standard models and includes examples and case studies covers turbo and super charging and automotive dependability and diagnosis accompanied by a web site hosting example models and problems and solutions modeling and control of engines and drivelines is a comprehensive reference for graduate students and the authors close collaboration with the automotive industry ensures that the knowledge and skills that practicing engineers need when analysing and developing new powertrain systems are also covered

modeling and control of batch processes presents state of the art techniques ranging from mechanistic to data driven models these methods are specifically tailored to handle issues pertinent to batch processes such as nonlinear dynamics and lack of online quality measurements in particular the book proposes a novel batch control design with well characterized feasibility properties

modeling and control of precision actuators explores new technologies that can ultimately be applied in a myriad of industries it covers dynamical analysis of precise actuators and strategies of design for various control applications the book addresses four main schemes modeling and control of precise actuators nonlinear control of precise actuators including sliding mode control and neural network feedback control fault detection and fault tolerant control and advanced air bearing control it covers application issues in the modeling and control of precise actuators providing several interesting case studies for more application oriented readers introduces the driving forces behind precise actuators describes nonlinear dynamics of

precise actuators and their mathematical forms including hysteresis creep friction and force ripples presents the control strategies for precise actuators based on preisach model as well as creep dynamics develops relay feedback techniques for identifying nonlinearities such as friction and force ripples discusses a mpc approach based on piecewise affine models which emulate the frictional effects in the precise actuator covers the concepts of air bearing stages with the corresponding control method provides a set of schemes suitable for fault detection and accommodation control of mechanical systems emphasizing design theory and control strategies the book includes simulation and practical examples for each chapter covers precise actuators such as piezo motors coil motors air bearing motors and linear motors discusses integration among different technologies and includes three case studies in real projects the book concludes by linking design methods and their applications emphasizing the key issues involved and how to implement the precision motion control tasks in a practical system it provides a concise and comprehensive source of the state of the art developments and results for modeling and control of precise actuators

the text is written from the engineer s point of view to explain the basic oncepts involved in feedback control theory the material in the text has been organized for gradual and sequential development of control theory starting with a statement of the task of a control engineer at the very outset the book is tended for an introductory undergraduate course in control systems for engineering students this text presents a comprehensive analysis and design of continuous time control systems and includes more than introductory material for discrete systems with adequate guidelines to extend the results derived in connection continuous time systems the prerequisite for the reader is some elementary owledge of differential equations vector matrix analysis and mechanics transfer function and state variable models of typical components and subsystems have been derived in the appendix at the end of the book most of the materials including solved and unsolved problems presented in the book have been class tested in senior undergraduates and first year graduate el courses in the field of control systems at the electronics and telecommunication engineering department jadavpur university matlab is the most widely used cad software package in universities throughout the world some representative matlab scripts used for solving problems are cluded at the end of each chapter the detailed design steps of fuzzy logic based controller using simulink and matlab has been provided in the book to give the student a head start in this emerging discipline a chapter has been included to deal with nonlinear components and their analysis g matlab and simulink through user defined s functions finally a chapter has been included to deal with the implementation of digital controllers on finite bit computer to bring out the problems associated with digital trollers in view of extensive use of matlab for rapid verification of controller designs some notes for using matlab script m files and function m files are included at the end of the book

this book reports on an outstanding research devoted to modeling and control of dynamic systems using fractional order calculus it describes the

development of model based control design methods for systems described by fractional dynamic models more than 300 years had passed since newton and leibniz developed a set of mathematical tools we now know as calculus ever since then the idea of non integer derivatives and integrals universally referred to as fractional calculus has been of interest to many researchers however due to various issues the usage of fractional order models in real life applications was limited advances in modern computer science made it possible to apply efficient numerical methods to the computation of fractional derivatives and integrals this book describes novel methods developed by the author for fractional modeling and control together with their successful application in real world process control scenarios

the high temperature solid oxide fuel cell sofc is identified as one of the leading fuel cell technology contenders to capture the energy market in years to come however in order to operate as an efficient energy generating system the sofc requires an appropriate control system which in turn requires a detailed modelling of process dynamics introducing state of the art dynamic modelling estimation and control of sofc systems this book presents original modelling methods and brand new results as developed by the authors with comprehensive coverage and bringing together many aspects of sofc technology it considers dynamic modelling through first principles and data based approaches and considers all aspects of control including modelling system identification state estimation conventional and advanced control key features discusses both planar and tubular sofc and detailed and simplified dynamic modelling for sofc systematically describes single model and distributed models from cell level to system level provides parameters for all models developed for easy reference and reproducing of the results all theories are illustrated through vivid fuel cell application examples such as state of the art unscented kalman filter model predictive control and system identification techniques to sofc systems the tutorial approach makes it perfect for learning the fundamentals of chemical engineering system identification state estimation and process control it is suitable for graduate students in chemical mechanical power and electrical engineering especially those in process control process systems engineering control systems or fuel cells it will also aid researchers who need a reminder of the basics as well as an overview of current techniques in the dynamic modelling and control of sofc

complexity and dynamic order of controlled engineering systems is constantly increasing complex large scale systems where large reflects the system s order and not necessarily its physical size appear in many engineering fields such as micro electromechanics manufacturing aerospace civil engineering and power engineering modeling of these systems often result in very high order models imposing great challenges to the analysis design and control problems efficient modeling and control of large scale systems compiles state of the art contributions on recent analytical and computational methods for addressing model reduction performance analysis and feedback control design for such systems also addressed at length are new theoretical developments novel computational approaches and illustrative applications to various fields along with an interdisciplinary focus

emphasizing methods and approaches that can be commonly applied in various engineering fields examinations of applications in various fields including micro electromechanical systems mems manufacturing processes power networks traffic control efficient modeling and control of large scale systems is an ideal volume for engineers and researchers working in the fields of control and dynamic systems

internal combustion engines still have a potential for substantial improvements particularly with regard to fuel efficiency and environmental compatibility these goals can be achieved with help of control systems modeling and control of internal combustion engines ice addresses these issues by offering an introduction to cost effective model based control system design for ice the primary emphasis is put on the ice and its auxiliary devices mathematical models for these processes are developed in the text and selected feedforward and feedback control problems are discussed the appendix contains a summary of the most important controller analysis and design methods and a case study that analyzes a simplified idle speed control problem the book is written for students interested in the design of classical and novel ice control systems

this book describes the interplay of mechanics electronics electrotechnics automation and biomechanics it provides a broad overview of mechatronics systems ranging from modeling and dimensional analysis and an overview of magnetic electromagnetic and piezo electric phenomena it also includes the investigation of the pneumo fluid mechanical as well as electrohydraulic servo systems modeling of dynamics of an atom particle embedded in the magnetic field integrity aspects of the maxwell s equations the selected optimization problems of angular velocity control of a dc motor subjected to chaotic disturbances with and without stick slip dynamics and the analysis of a human chest adjacent to the elastic backrest aimed at controlling force to minimize relative compression of the chest employing the lqr this book provides a theoretical background on the analysis of various kinds of mechatronics systems along with their computational analysis control optimization as well as laboratory investigations

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